GENERALIZATION OF THE H_p -THEOREM IN A SPACE OF CONSTANT CURVATURE

Hilário Alencar Antonio Gervasio Colares

Let $x: M^n \to \mathbb{R}^{n+1}$ be and isometric immersion of an oriented Riemannian manifold M^n with unit normal vector ν , mean curvature Hand support function $p = -\langle x, \nu \rangle$. The H_p -Theorem says that if M^n is compact and

$$H_p = 1,$$

then $x(M^n)$ is a round sphere ([3]).

Here we announce two generalizations of the H_p -Theorem. The proofs will appear elsewhere.

Will appear ensemble? Denote by Q_c^{n+1} an *n*-dimensional simply connected space of constant curvature *c*. If $p_0 \in Q_c^{n+1}$ we denote $r(\cdot) = d(\cdot, p_0)$ the distance function relative to p_0 and we write grad *r* for the gradient of *r* in Q_c^{n+1} . Let $x: M^n \to R^{n+1}$ be an isometric immersion of a Riemannian manifold M^n oriented by a unit vector ν . We call $X = S_c$ grad *r* the position vector of the immersion with respect to p_0 , where $S_c(r) = r, \frac{\sin(r\sqrt{c})}{\sqrt{c}}$ or $\frac{\sinh(r\sqrt{-c})}{\sqrt{-c}}$, according c = 0, c > 0 or c < 0. The function $p = -\langle X, \nu \rangle$ will be called the support function of the immersion. We denote $\theta_c = \frac{d}{d_c} S_c(r)$.

Theorem 1. ([1]) Let $x: M^n \to Q_c^{n+1}$ be an isometric immersion of a compact oriented Riemannian manifold M^n with mean curvature H and support function p. Then

$$H_p - \theta_c$$

does not change sign if and only if $x(M^n)$ is a geodesic sphere.

A proof of this theorem is obtained from the following

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Lemma. In the conditions of Theorem 1, if Δ is the Laplacian of M^n , then

$$\frac{1}{2}\Delta\langle X,X\rangle = -c\,S_c^2\,|(\text{grad }r)^T|^2 - n\theta_c(H_p - \theta_c).$$

Theorem 2. Let $x: M^n \to S^{n+1}(c)$ be an isometric immersion of a compact oriented Riemannian manifold M^n into the (n + 1)-sphere of radius $\frac{1}{\sqrt{c}}$, with unit normal vector ν , mean curvature H > 0 and support function p. If

H = p,

then $x(M^n)$ is a geodesic sphere.

This theorem has been proved by G. Huisken ([2]) when the ambient space is the Euclidean space \mathbb{R}^{n+1} .

References

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Hilário Alencar Departamento de Matemática Univ. Federal de Alagoas 57000 Maceió, Alagoas

Antonio Gervasio Colares Departamento de Matemática Univ. Federal do Ceará

Univ. Federal do Ceará 6000 Fortaleza, Ceará

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